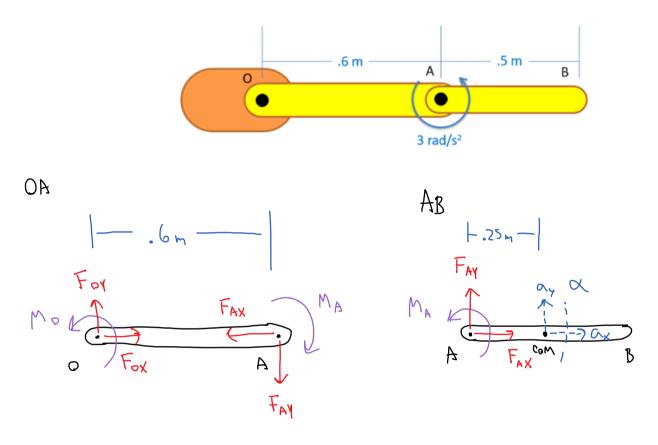
Problem 1

A robotic arm has two sections (OA and AB) with section OA having a mass of 10 kg and section AB having a mass of 7 kg. Treat each section as a slender rod. If we wish to accelerate member AB from a standstill at a rate of 3 rad/s2 and keep the right section stationary, what moments must we exert at joints O and A?



Start with kinematics of AB

$$\alpha_{x} = - r \omega^{2} = 0$$

$$\alpha_{y} = r \alpha = (.25 \text{ m})(3 \text{ rad/s}^{2}) = .75 \text{ m/s}^{2}$$

$$\alpha_{z} = 3 \text{ rad/s}^{2}$$

Kinetics of AB

$$\begin{aligned}
\xi F_{X} &= F_{AX} = O \\
\xi F_{Y} &= F_{AY} = (7 \text{ kg})(.75 \text{ m/s}^{2}) \\
F_{AY} &= 5.25 \text{ N} \\
& \underbrace{F_{AY} = 5.25 \text{ N}}_{\text{Com}} = M_{A} - (.25 \text{m})(F_{AY}) = I \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = 5.25 \text{ N}}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F_{AX} = O}_{\text{AY} = 0} \\
& \underbrace{f_{X} = F$$

$$M_A = 1.3125 = .4375$$

$$M_A = 1.75 N_m$$

Kinetics of OA

$$\Sigma F_{x} = F_{0x} - 0 = 0$$

$$\frac{F_{0x} = 0}{2F_{y} = F_{0y} - 5.2S} = 0$$

$$\frac{F_{0x} = 5.2S \, N}{2F_{0y} = 5.2S \, N}$$

$$\Sigma M_{0} = M_{0} - 1.7S - (.6)(5.2S) = 0$$

$$M_{0} = 4.9 \, N_{M}$$